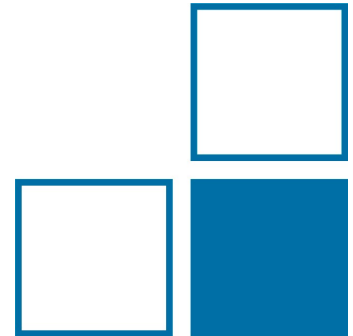


Are We There Already or Can We Do Better?

– A Slightly Different Angle on Safe Implant Scanning

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Declaration of ~~Financial~~ Interests or Relationships

Speaker Name: Bernd Ittermann

Caution: some serious advertising ahead

Alternative title:



If our implant (lead/electrode) had a sensor ...

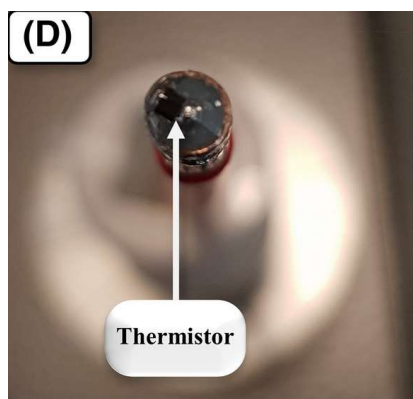
... and our scanner a parallel transmit (pTx) system,

what could that be good for ?

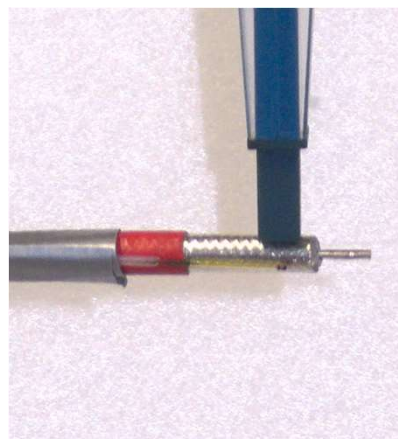
- Implant sensors and how to utilize them
- pTx: combining image quality and safety
- Some aspects of a practical implementation
- Conclusion

Are implant sensor doable?

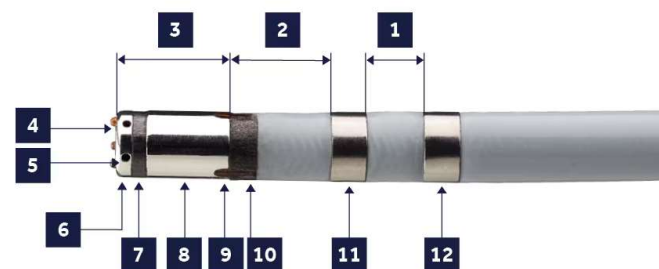
- yes



B. Silemek et al., MRM 2022



J. Petzold et al., ISMRM 2023
"remote" implant sensor



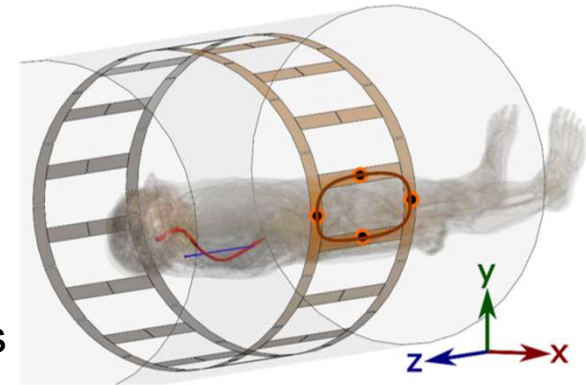
global.Medtronic.com: ablation catheter tip with 6 thermocouples

- ok, they may be doable, but are they worth it?

Simulation setup

The model

- Generic 8-ch body coil at 3 T
- ‘Duke’, dummy implant touching spinal cord, heart at $z = 0$
Sim4Life 5.0, 2 mm iso, 48 ports, co-simulations, Pennes, VOP’s

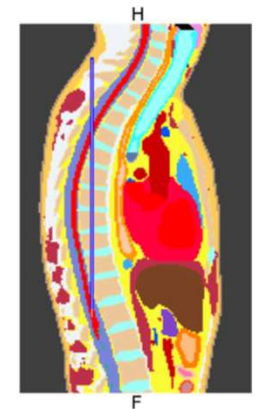
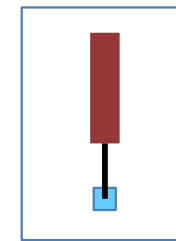


The “sensors”

- Computed physical quantities at or around implant tip
 - SAR , $|E_z|^2$, $|B_1|^2$, dT/dt averaged over $(4 \text{ mm})^3$ around tip
 - I_{RF} at $d_1 = 10 \text{ mm}$ or $d_2 = 250 \text{ mm}$ from tip

The hazard metrics

- SAR_{pt} , SAR_{10g} , T_{SS} , ΔT_{imp}



Data processing: the native case

Calculation of point Q-matrices:

$$\text{SAR}(\mathbf{r}, \mathbf{u}) = \frac{\sigma(\mathbf{r})}{2\rho(\mathbf{r})} |\mathbf{E}(\mathbf{r}, \mathbf{u})|^2 = \mathbf{u}^\dagger \mathbf{Q}_{\text{pt}}(\mathbf{r}) \mathbf{u}$$

excitation voltage vector

Averaging to get 10g Q-matrices + head + whole body + partial body:

$$\mathbf{Q}_{\text{pt}}(\mathbf{r}) \rightarrow \mathbf{Q}_A^{(k)}$$

Normalization to IEC limits L :

$$\hat{\mathbf{Q}}_A^{(k)} = \frac{\mathbf{Q}_A^{(k)}}{L^{(k)}}$$

VOP calculation:

$$\hat{\mathbf{Q}}_A^{(k)} \rightarrow \hat{\mathbf{Q}}^{(k)}$$

$\max_k \mathbf{u}^\dagger \hat{\mathbf{Q}}^{(k)} \mathbf{u}$	≤ 1	$\stackrel{\text{def}}{=} u$	u is safe
$\max_k \mathbf{u}^\dagger \hat{\mathbf{Q}}^{(k)} \mathbf{u}$	> 1	$\stackrel{\text{def}}{=} u$	u is unsafe

Q_S – the sensor Q matrix

$$\text{SAR}(\mathbf{u}) = \mathbf{u}^\dagger \mathbf{Q}_{\text{SAR}} \mathbf{u} \quad \leftrightarrow \quad \text{Sensor signal } X(\mathbf{u}) = \mathbf{u}^\dagger \mathbf{Q}_S \mathbf{u}$$

$$Q_{S,kl}^X = \begin{cases} (X_{kl} - X_k - X_l) + j(X_{kl}^\dagger - X_k - X_l) & \text{for } k \neq l \text{ and } k < l \\ (X_{kl} - X_k - X_l) - j(X_{kl}^\dagger - X_k - X_l) & \text{for } k \neq l \text{ and } k > l \\ 2X_k & \text{for } k = l \end{cases}$$

X_k : sensor signal if only channel k transmits

X_{kl} : sensor signal if channels k and l transmit in phase

X_{kl}^\dagger : sensor signal if channels k and l transmit 90° out of phase

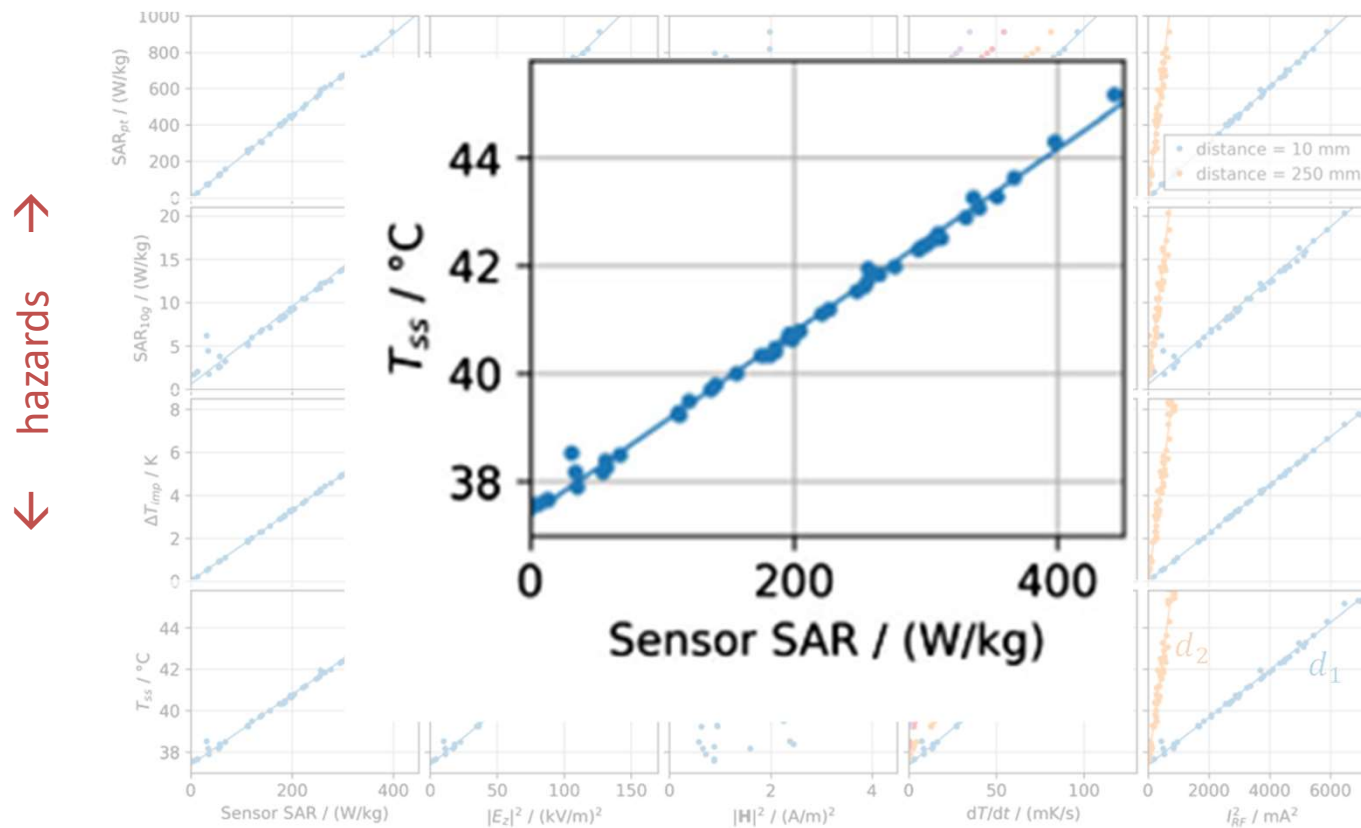
N channels $\rightarrow N^2$ measurements $\rightarrow \mathbf{Q}_S$ determines sensor response to all possible excitations

Normalization: $\hat{\mathbf{Q}}_S = \mathbf{Q}_S / q_{\text{lim}}$ q_{lim} = max. permissible sensor reading, to be defined

Sensor calibration

- 100 random excitations → calculate sensor signals and hazard measure

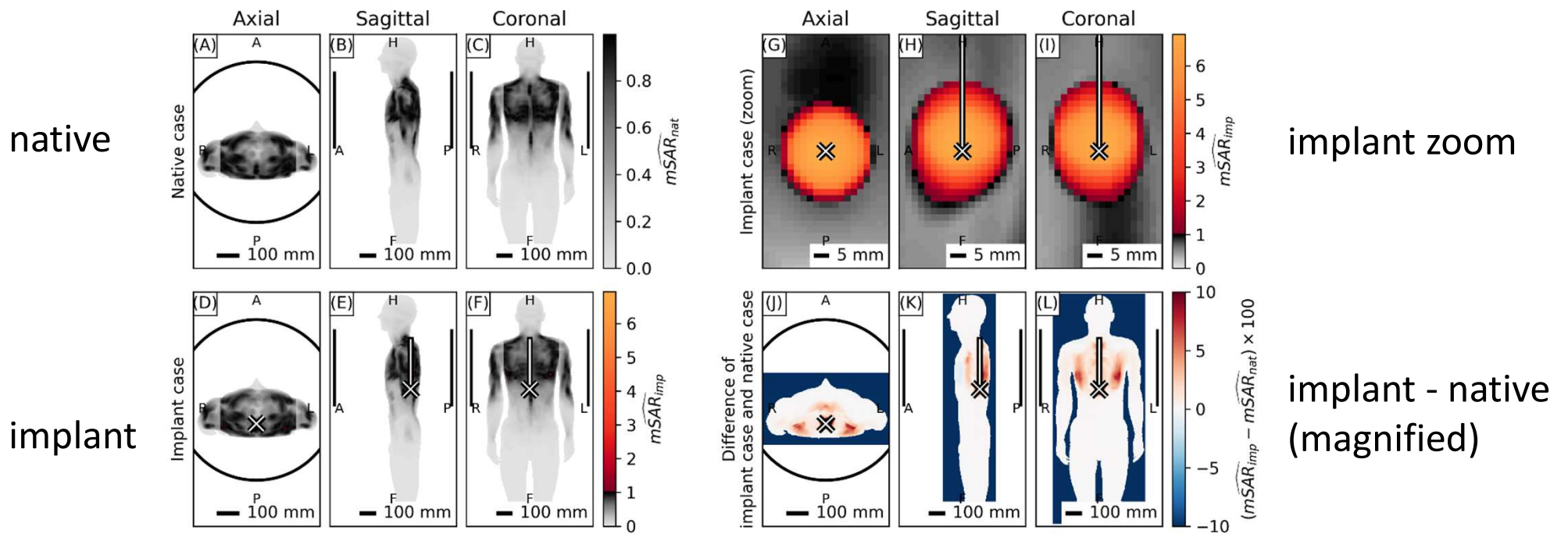
← sensors →



Native safety vs implant safety

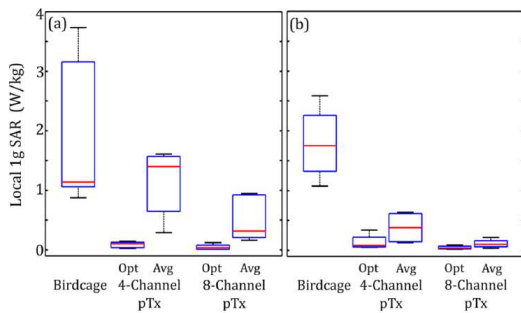
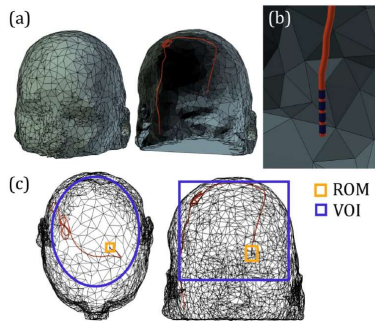
Same excitation vector with or without implant (\hat{Q}_s ignored)

- normalized SAR MIPs \rightarrow single hotspot at implant tip + minor global effects



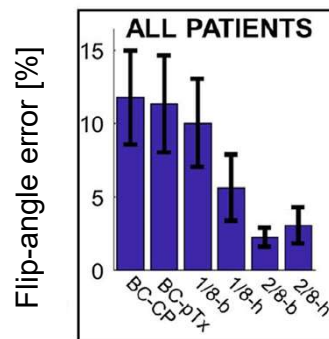
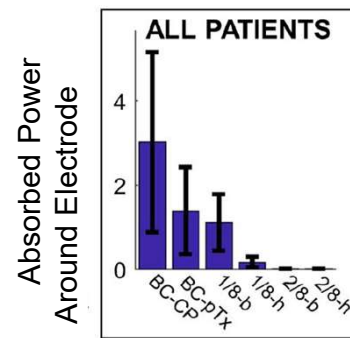
Step 2: pTx

- pTx is only good for 7T, right?
- Well, not really



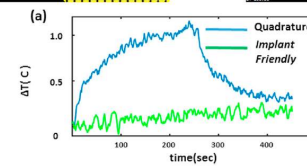
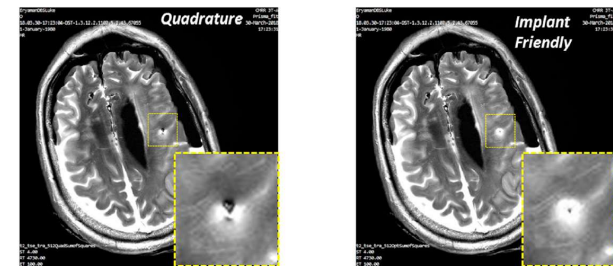
McElcheran CE et al., MRM 2017
 McElcheran CE et al., Sci Rep 2019

3T



Guerin B et al., MRM 2020

3T

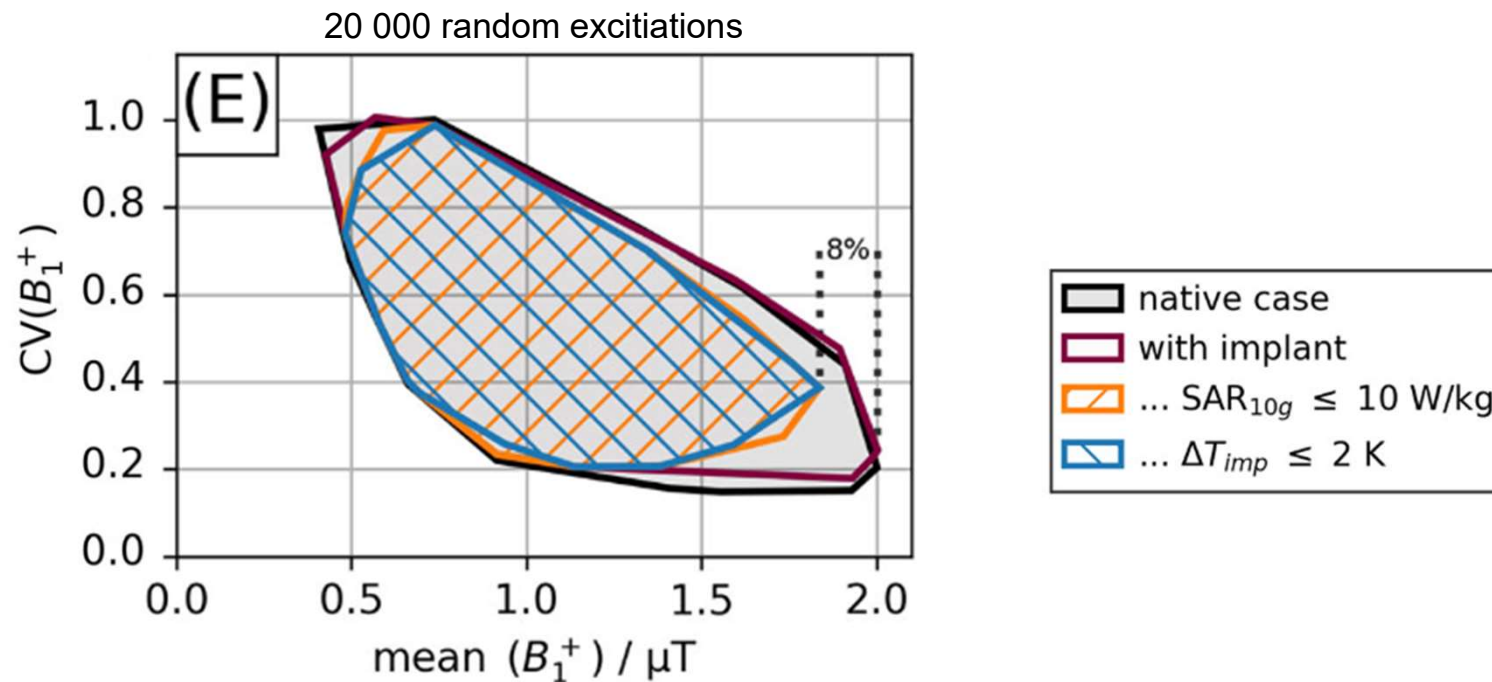


3T

Eryaman Y et al., NeuroImage 2019

pTx and image quality

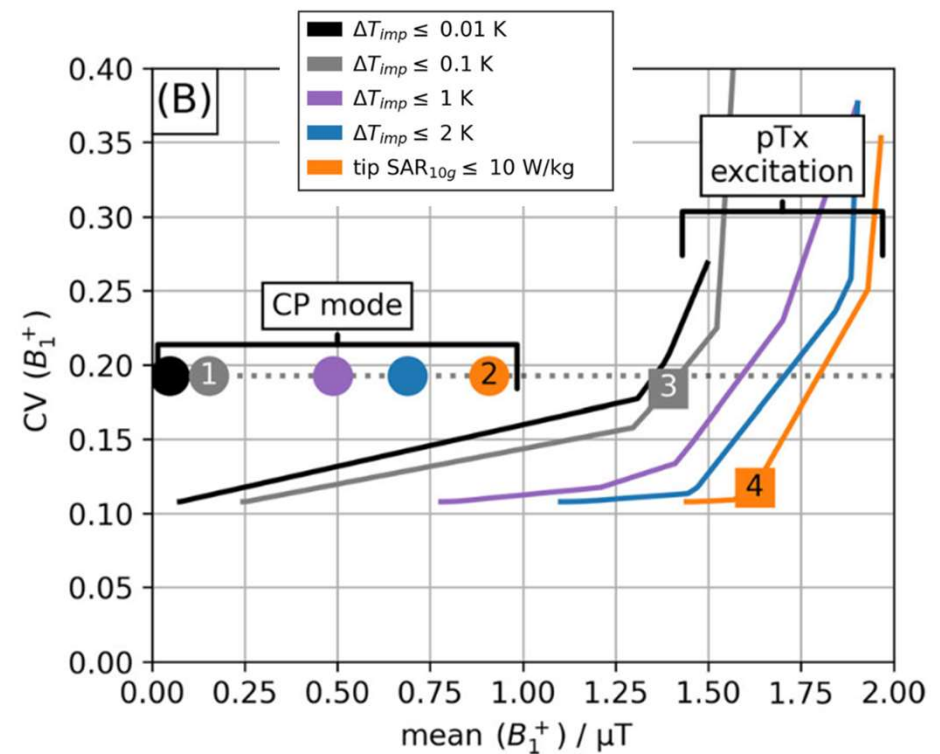
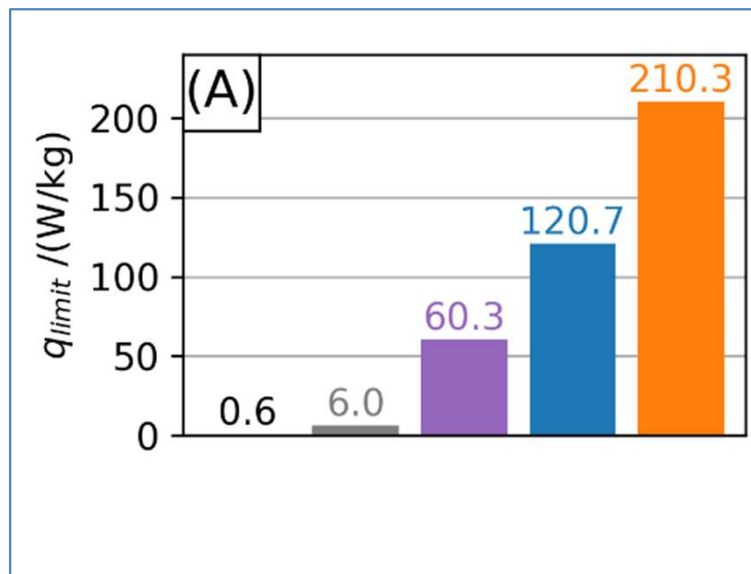
- Simplest possible pTx application: static RF shimming
- Quality metric: $\text{mean}(B_1^+)$, $\text{CV}(B_1^+)$



J Petzold et al., NMR Biomed 2023

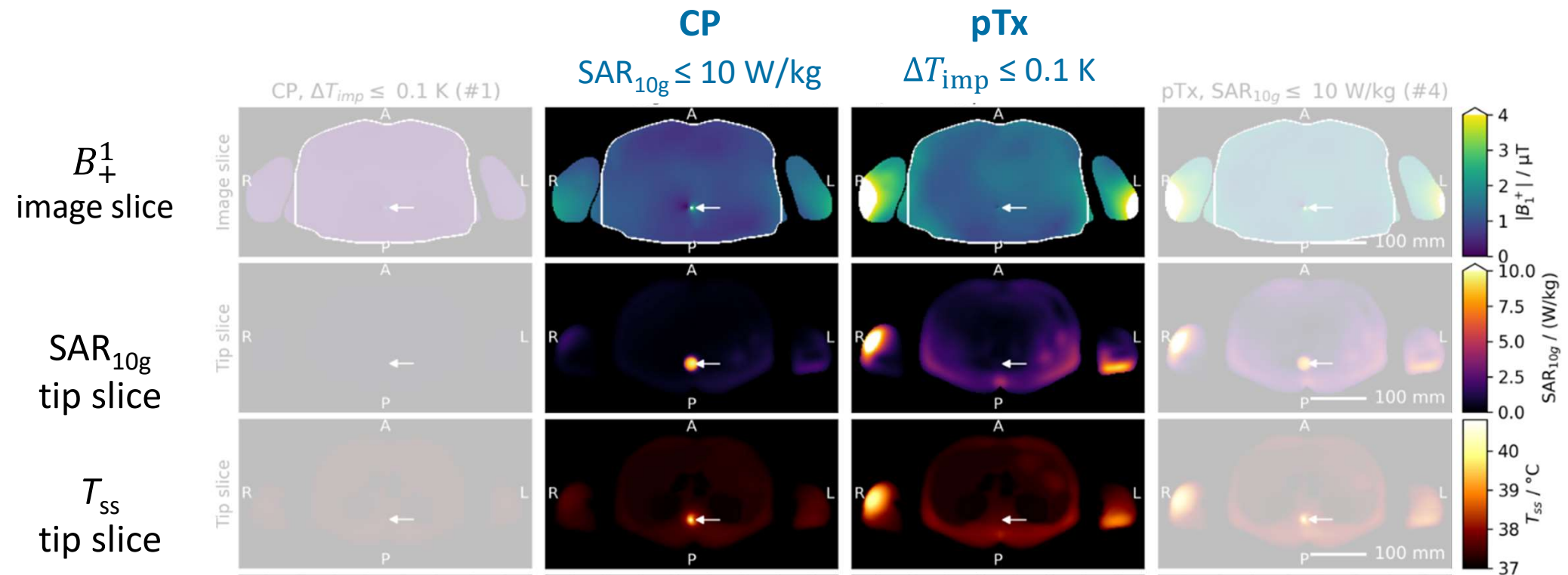
Optimizing image quality

- trade-off between high $\text{mean}(B_1^+)$ and low $\text{CV}(B_1^+)$
- image quality is the target, safety the constraint



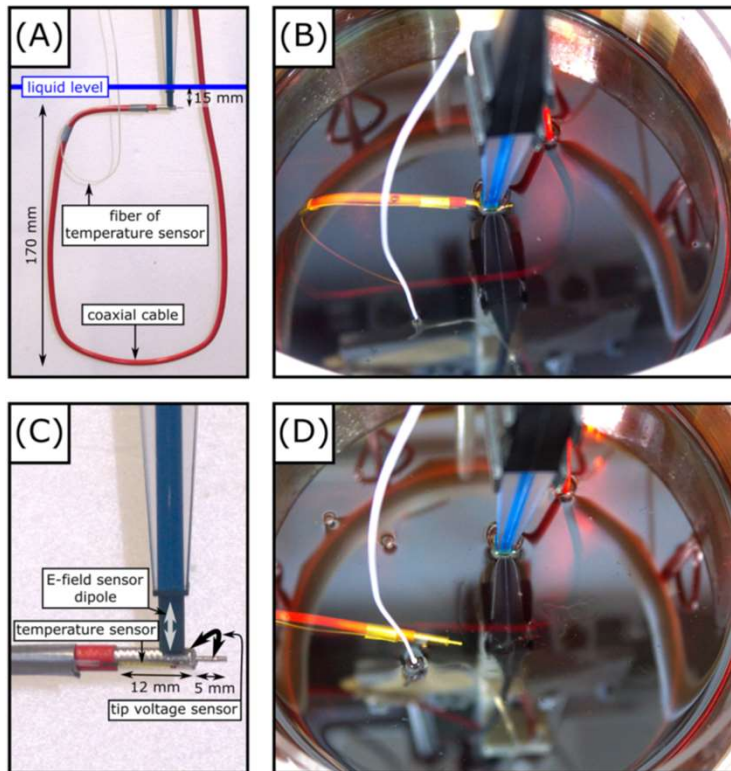
B_+^1 maps

- trade-off between high $\text{mean}(B_+^1)$ and low $\text{CV}(B_+^1)$

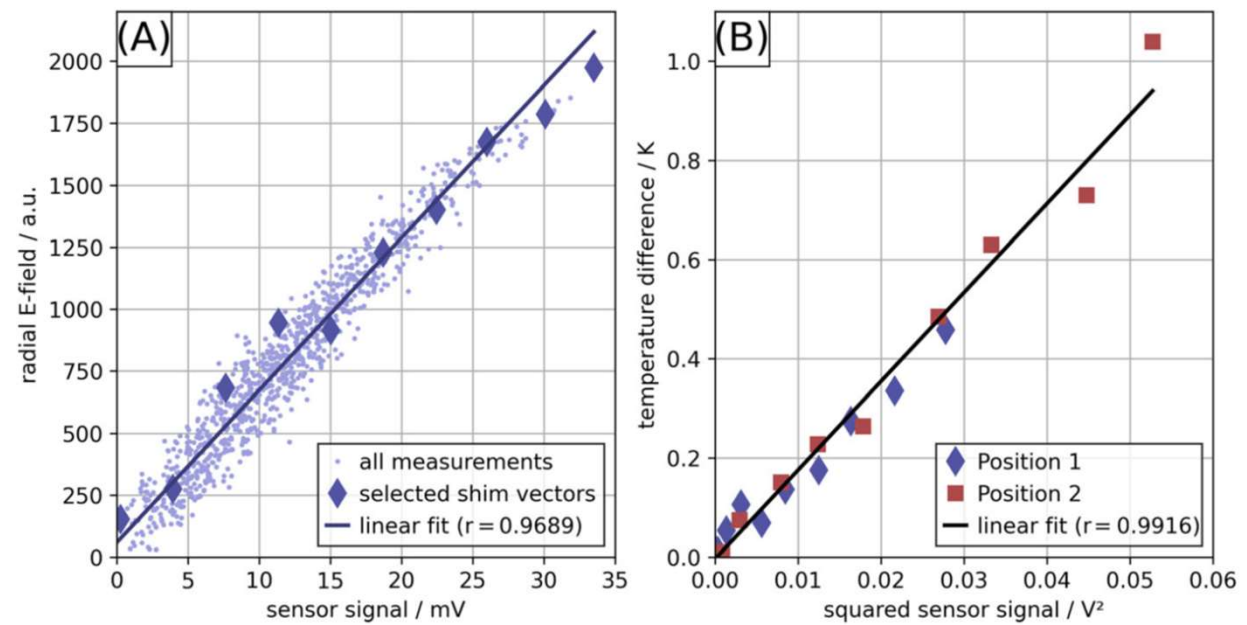


Simulate and validate

- experimental calibration of the implant sensors against external probes

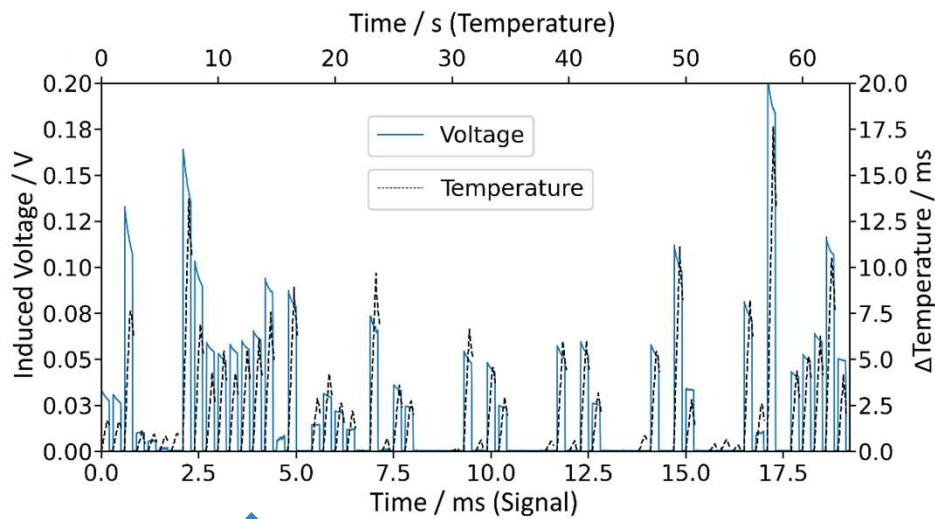


J Petzold et al., ISMRM 2023



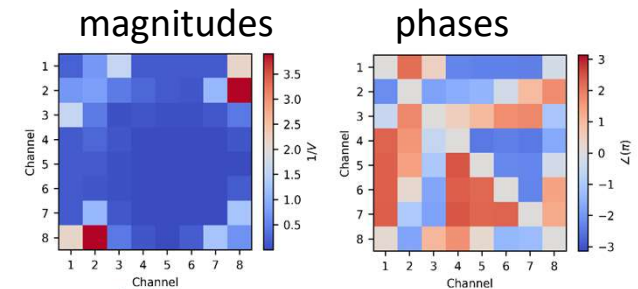
Measuring Q_s

- Measurements for a T or E-field sensor



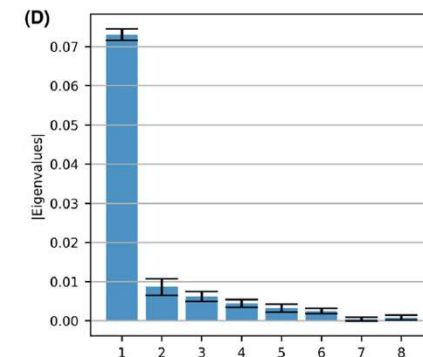
1

$$Q_s^E$$



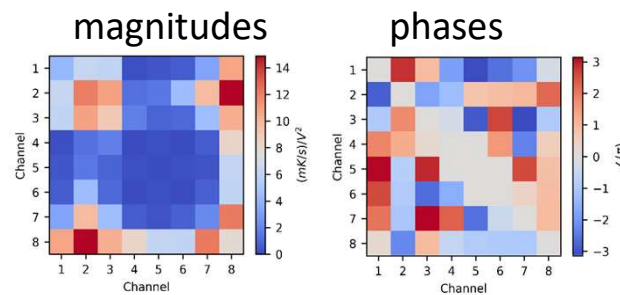
2

Q_s Eigenvalues



1

$$Q_s^T$$



2

Q_S vs the state of the art?

- ISO 10 974, Tier 3: the Transfer Function (TF)

From: SM Park, R Kamondetdacha, JA Nyenhuis, JMRI 2007

$$E_S(P) \approx E_1(P) \int_0^L S_1(s) E_{\text{tan}}(s) ds \quad (2)$$

$$\alpha \equiv \int_0^L S_1 E_{\text{tan}} ds \quad (3)$$

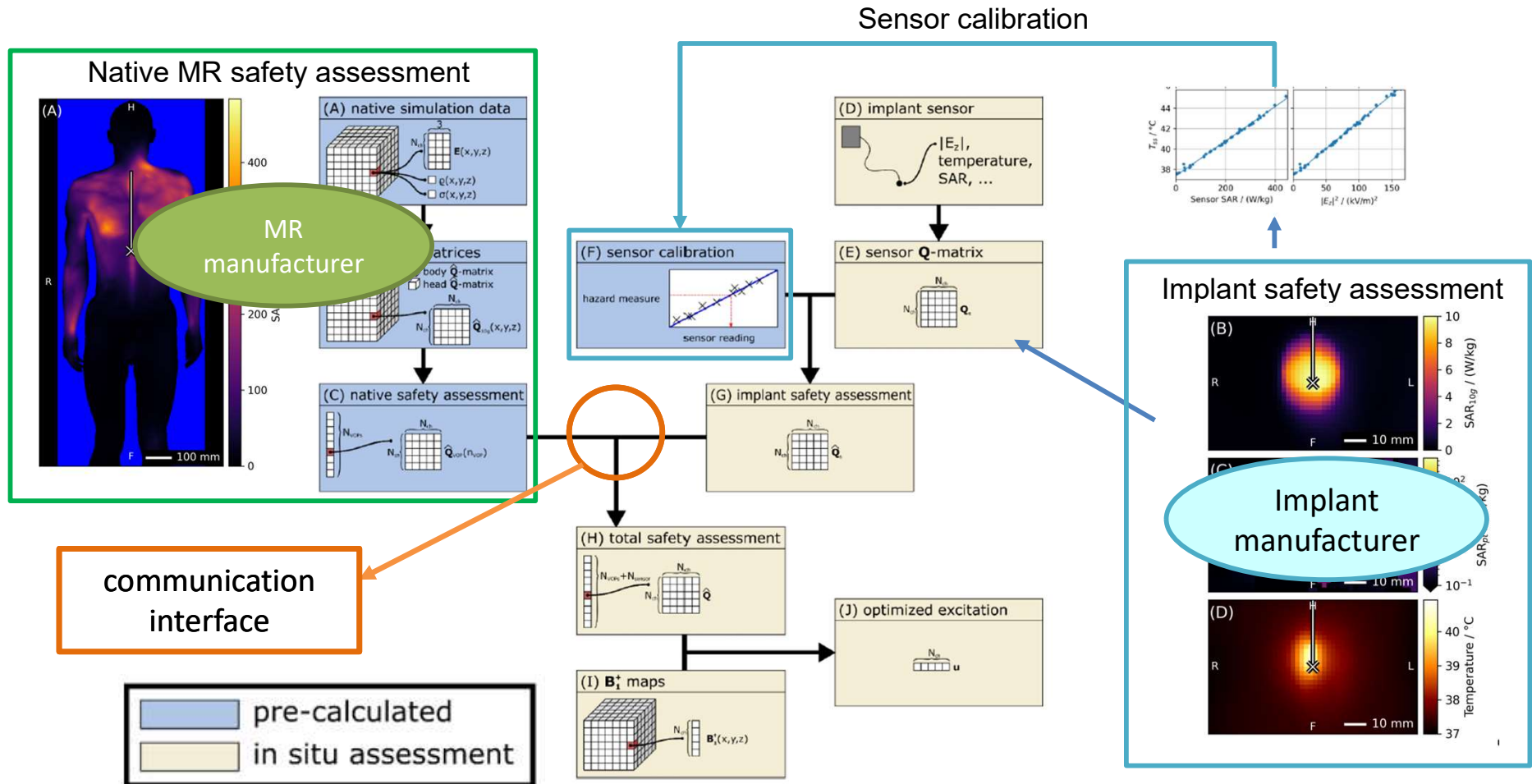
$$\text{SAR}(\mathbf{u}) = \mathbf{u}^\dagger |\alpha|^2 \mathbf{u} \quad (4)$$

Reminder:

Sensor signal: $X(\mathbf{u}) = \mathbf{u}^\dagger Q_S \mathbf{u}$

- Q_S is the Transfer Function integral
 - for the actual patient in the scanner
 - evaluated along the actual implant trajectory
 - and the actual E-fields in the body

An 'integrated safety concept'



- Sensor based implant safety concept

- Restrictions themselves, are we still responsible then?

- In situ assessment

- patient's safety
- implant temperature
- MR scanner

But if scanner and implant set the scan conditions by themselves, are we still responsible then?



Sorry guys, but no: **you're out!**

- Ultimate goal

- Scanner and implant communicate directly, negotiate RF settings

Acknowledgements



ISMRM Safety SG award 2023
3rd prize

Johannes Petzold



ISMRM Safety SG award 2023
1st prize

Berk Silemek



Lukas Winter



Frank Seifert

MGH: Bastien Guerin (DBS trajectories)

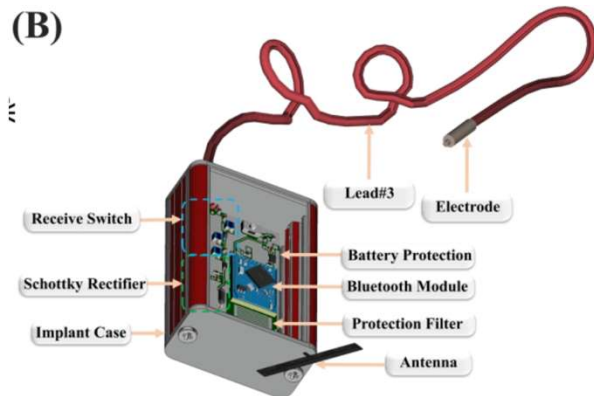
Funding: EU metrology research programs



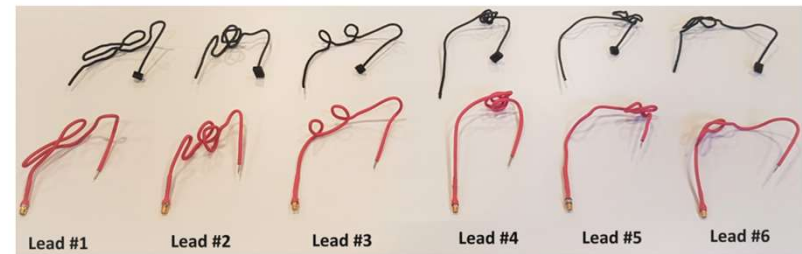
This work has received funding from the European Metrology Programme for Innovation and Research (EMPIR), co-financed by the European Union's Horizon 2020 Programme and by the Participating States, under grant numbers 17IND01 MIMAS and 21NRM05 STASIS.

How to get the signal out?

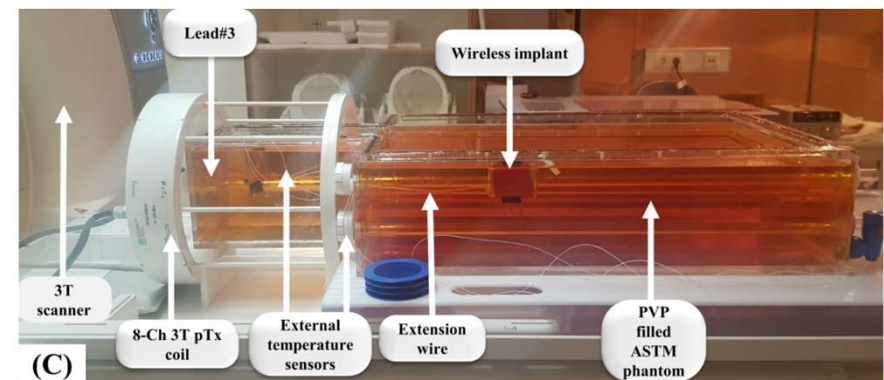
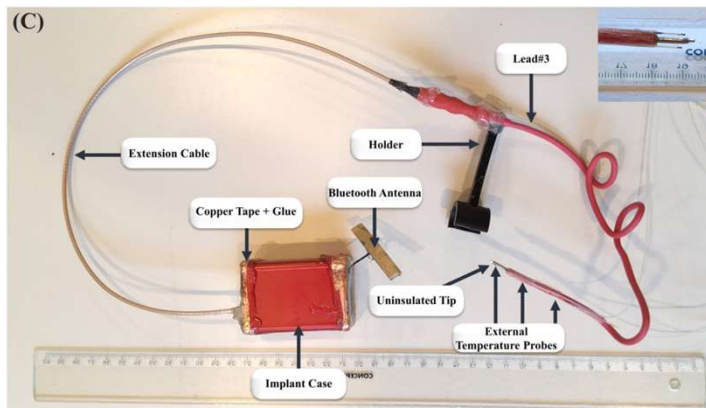
- Sensor embedded wireless reference implant



Realistic DBS lead trajectories (B Guerin et al, Phys Med Biol 2019)



3T experimental setup



B Silemek et al., MRM (under review)

Bernd Ittermann: Are we there already?

Sensor calibration

- 100 random excitations → calculate sensor signals and hazard measure

